

# Emulation library for a modular cyber-physical systems simulation platform

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# Problem

- › CPS tests may be expensive, i.e. aerospace systems
- › CPS tests can be destructive, i.e. automotive systems
- › Shorter development cycles require faster development

# Our approach

## › Emulation

- › Replicate the behavior of the real hardware, at the **functional** level
- › Otherwise these tests can't be taken into account while testing these systems

# Emulator requirements

- › Full-system emulation
- › Emulation of multiple architectures
- › Adequate licensing
- › Multi-processor system emulation capabilities

# Candidates

> Bochs

> Gem5

> Emul8

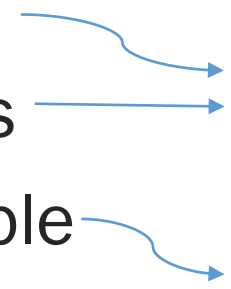
> QEMU



Inadequate

Emulator of  
choice

# QEMU's characteristics

- › NOT user friendly
  - › Difficult to integrate with other modules
  - › Executes at the maximum speed possible
- First problem
- Second problem
- 

# Solving the first problem

- › Library to make QEMU more user-friendly and integrable with other modules
- › Written in C++



# QEMU-Lib

- › QEMU instance independence
- › Communicating with QEMU

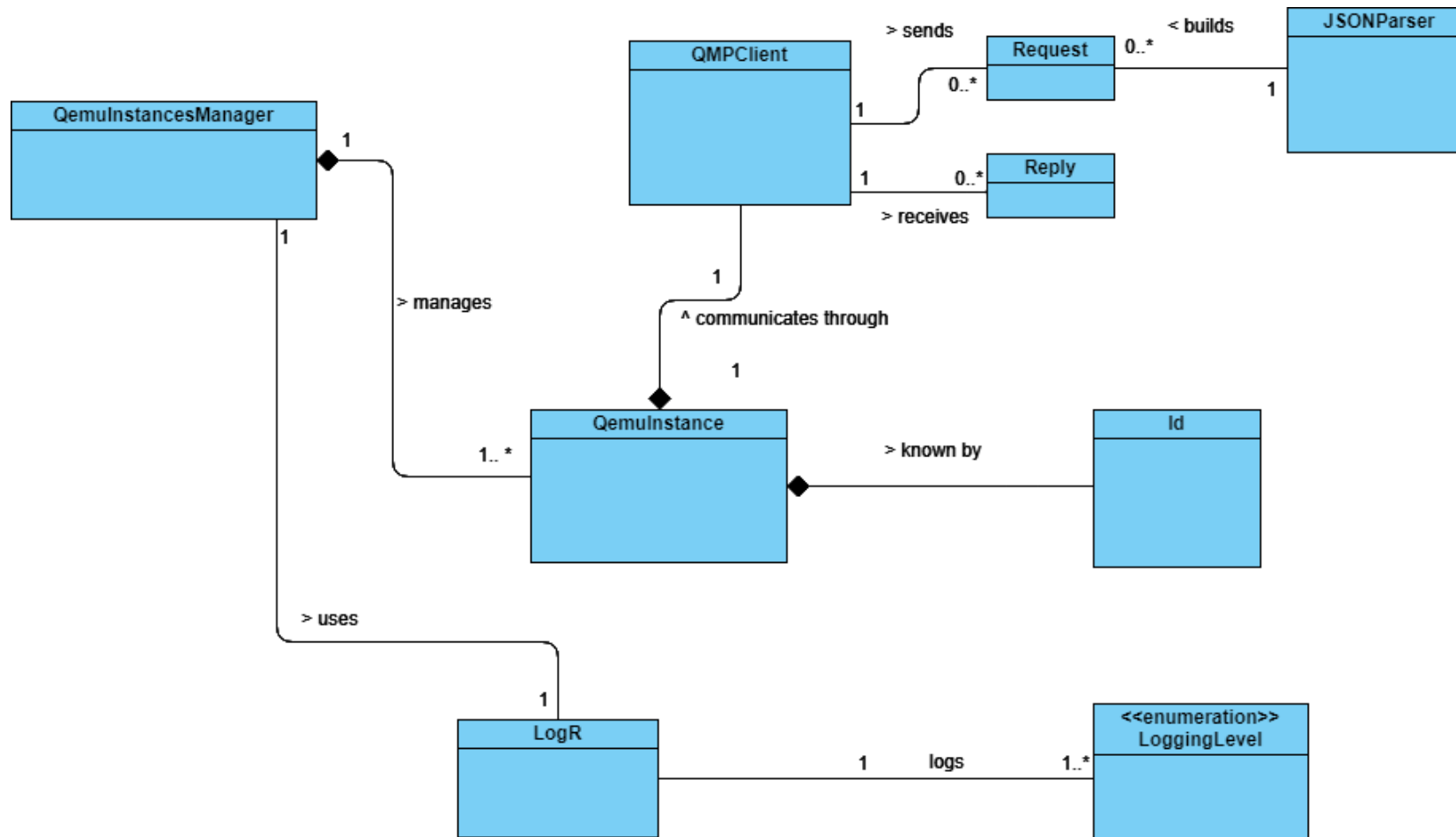
# QEMU instance independence

- › One virtual machine is one QEMU instance
- › Library should be able to communicate with one independent instance

# Communicating with QEMU

- › QEMU Monitor
- › QEMU Machine Protocol (QMP) via TCP
- › Human-Monitor Commands (HMP) via TCP
- › Library should parse simpler commands into QMP and HMP valid commands

# Library architecture

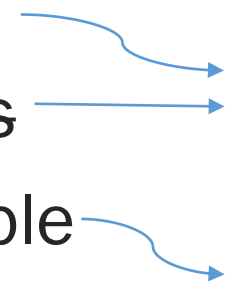


# Solution of the first problem

With the solution implemented it is now possible to:

- Provide control of individual instances
- Provide ease of access on configuring virtual machines
- Provide ease of integration with other modules (by exposing these features in a module to be consumed by other modules)

# QEMU's characteristics

- ~~NOT user friendly~~
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# Solving the second problem

- By nature, QEMU runs at the maximum speed allowed by the *host CPU*
- Provide a mechanism to **throttle** the **virtual CPU** and the **virtual clocks**, in order to achieve a faithful replication of the functional behavior of the real system

# The throttle mechanism

- Reduce execution speed
- Reflect execution speed changes in QEMU's **clocks**



# Reducing execution speed

- QEMU introduced a migration feature in version **2.4**
- This feature throttles the CPU in order to be able to complete **live migrations** (else these migrations could not complete)
- The **throttling** is in actuality induced via making the CPU sleep in timeslices measured in **microseconds**, varying these timeslices according to a percentage
- We take advantage of these facts and expose pieces of this **throttling** feature as a command

# Reducing execution speed

## However:

- The rest of the system does not reflect this change in the execution speed, i.e., the **clocks**
- This may cause desynchronization issues between components and communication with other systems

# Reflect execution speed changes in QEMU's clocks

- We took advantages of the existing 'pause' mechanism, which pauses the virtual machine
- When the machine is paused, the virtual clock (QEMU\_CLOCK\_VIRTUAL) is paused
- We used pieces of the pause code to effectively stop the clock while the machine is **throttling**, making it only increase when the machine is actively executing

# Solution of the second problem

The throttle mechanism provides:

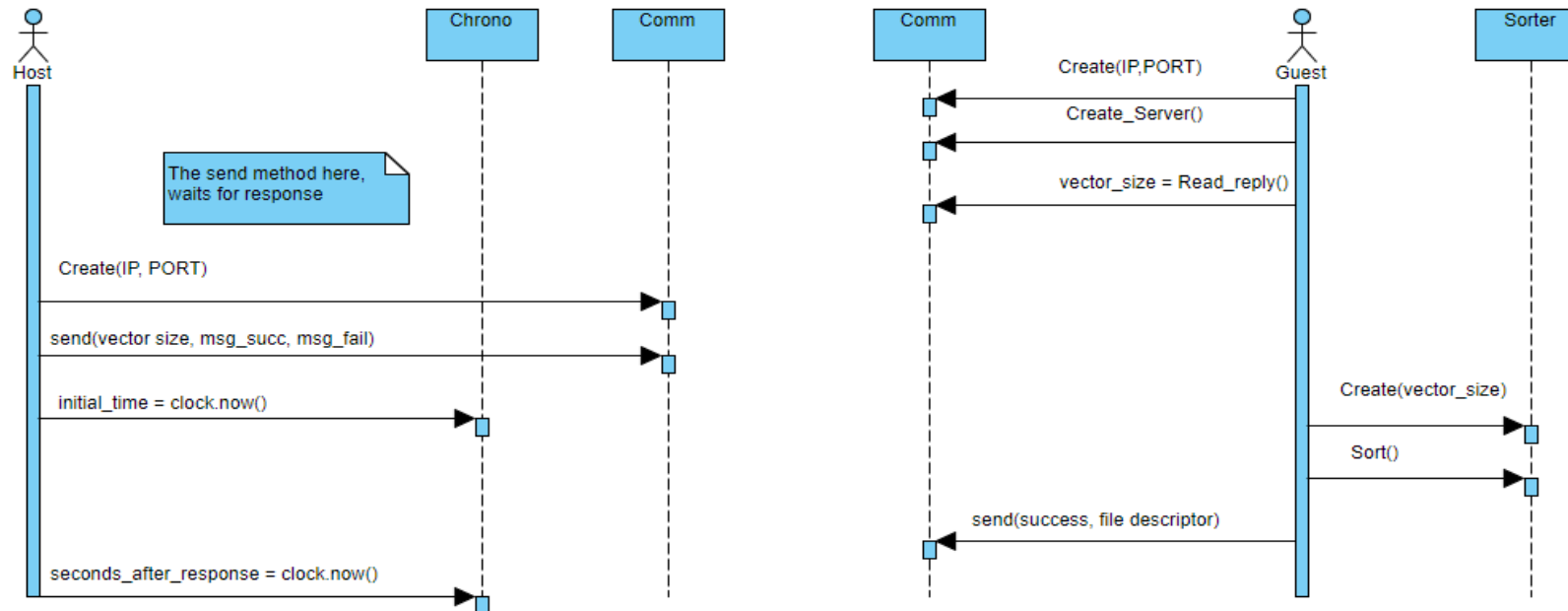
- A command which **throttles** the virtual machine according to a percentage
  - This change in execution speed is now reflected in the virtual machine's **clocks**

# Results of the study

- Task execution times were measured via a client-server application, since the throttled machine's measures would be incorrect (since the clocks reflect the speed change)
- The task is the sorting of a vector of size 250000
- Sorting algorithm has  $n * \log(n)$  complexity
- The measurements were performed in a x64 virtual machine running Ubuntu

# Results of the study

## > Test application architecture



# Results of the study

- › Executing a task which takes 1.2559 seconds to complete with 0% throttle



# Results of the study

- As we can see, this same task, when executed in a machine submitted to 90% **throttling**, executes in approximately 29.39 seconds





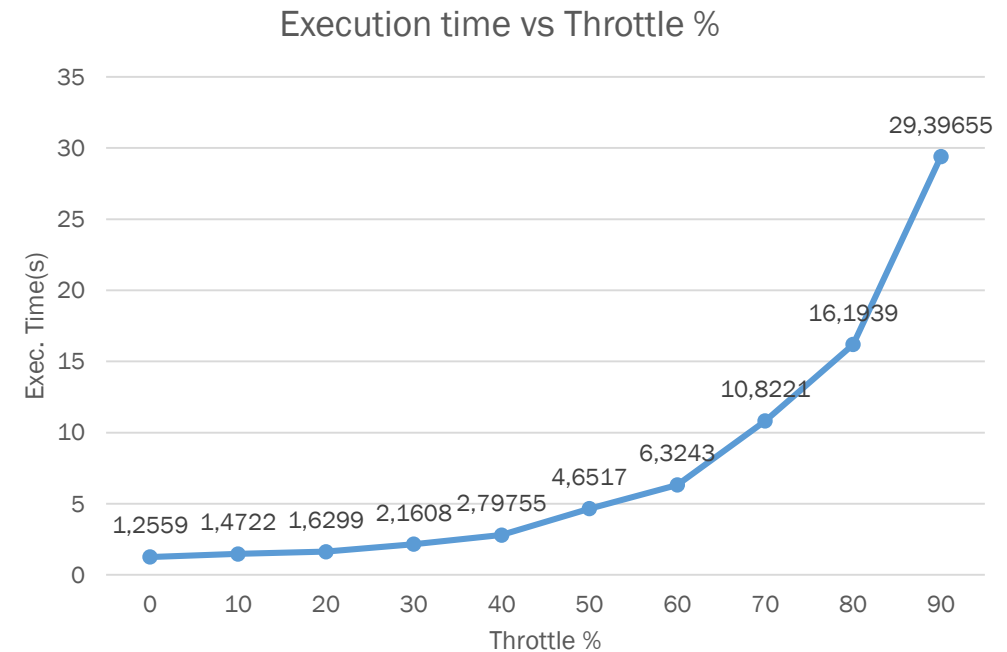
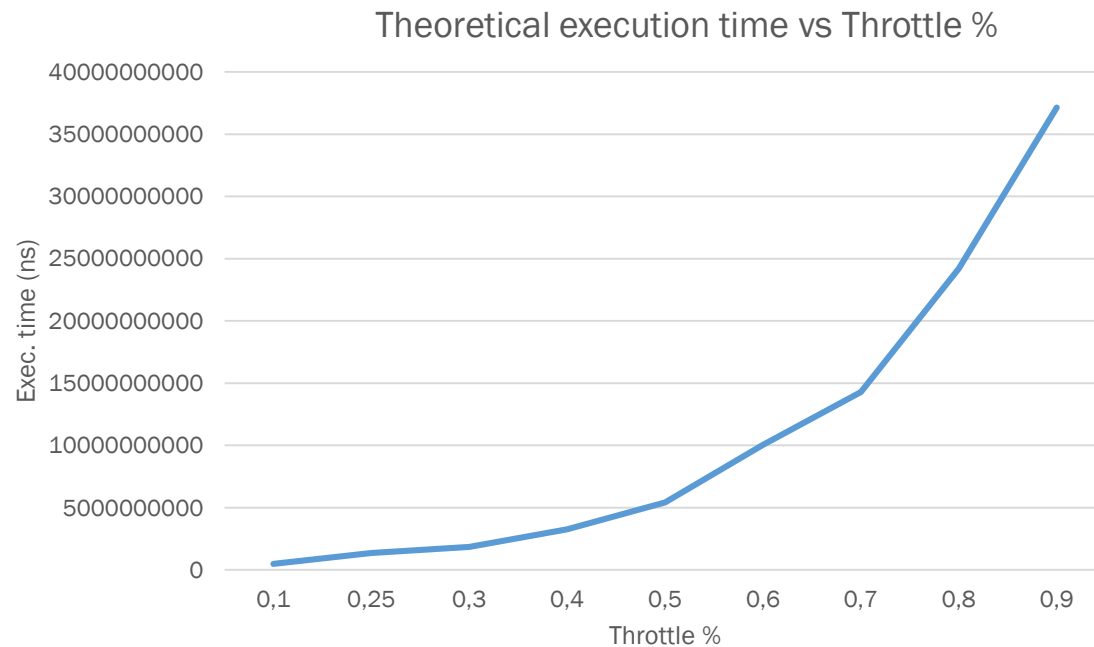
# Results of the study

➤ After 40% throttle the curve begins to accentuate exponentially



# Results of the study

> We can see that the measured curve is similar to the one obtained in a theoretical study of the throttle mechanism



# Concluding remarks

- ~~> NOT user friendly~~
  - ~~> Difficult to integrate with other modules~~
    - > QEMU is now easier to use and easier to integrate with other modules
  - ~~> Executes at the maximum speed possible~~
    - > QEMU's execution speed can now be controlled
- First problem
- Second problem

# Thank you for your time